

# Solving Life-Cycle Models with a Rich Asset Structure using Deep Learning

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based on joint work with Jan Žemlička,<sup>2,3</sup> Luca Gaegauf,<sup>2</sup> and Simon Scheidegger<sup>4,5</sup>

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# Motivation

- | Economic models to study questions related to **aggregate risk** and **asset pricing**, often require **global solution methods** to compute equilibria
- | Computing a functional rational expectations equilibrium amounts to computing a **set of functions**,  $f_i$ , mapping the **state of the economy**,  $\mathbf{x}$ , to **endogenous outcomes**  $f_i(\mathbf{x})$ :

$$f_i : D \subseteq \mathbb{R}^{N_{in}} \rightarrow \mathbb{R} : \underbrace{\mathbf{x}}_{\text{state}} \mapsto \underbrace{f_i(\mathbf{x})}_{\text{endogenous variables}}, \text{ s.t. : } \underbrace{\mathbf{G}(\mathbf{x}, f_1, \dots, f_{N_{out}})}_{\text{equilibrium conditions}} = 0$$

- | This can be a computationally demanding task, especially when
  - | the **state** of the economy is **high-dimensional**
  - | the equilibrium **functions** are **nonlinear**
- | Both often happens for **Overlapping Generations (OLG)** models:
  - | the state includes the wealth distribution across age-groups
  - | young households are often constrained
  - | may want to account for portfolio decomposition and volatility of labor income, both of which have strong lifecycle components

# This talk

- | Basic solution method developed in Azinovic et al. (2022)
- | More recent progress on portfolio choice and market clearing neural network architectures developed in Azinovic and Žemlička (2023)

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- | More recent progress on portfolio choice and market clearing neural network architectures developed in Azinovic and Žemlička (2023)
- | Other papers on deep learning based solution methods I learned a lot from: Maliar et al. (2021); Kase et al. (2023); Gu et al. (2023); Kahou et al. (2021); Han et al. (2022); Valaitis and Villa (2024); Kahou et al. (2022); Fernández-Villaverde et al. (2023); Barnett et al. (2023); Jungerman (2023); Kahou et al. (2024)

# Deep Equilibrium Nets

# Violations of equilibrium conditions as loss function

Basic idea in Azinovic et al. (2022): write equilibrium conditions as

$$\mathbf{G}(\mathbf{x}; \mathbf{f}) = 0 \quad \forall \mathbf{x}$$

$\mathbf{G}$  : equilibrium conditions: FOC's, market clearing, Bellman equations, ...

$\mathbf{x}$  : state of the economy

$\mathbf{f}$  : equilibrium functions:

Approximate  $\mathbf{f}$  by neural network  $N$

$$N(\mathbf{x}) \approx \mathbf{f}(\mathbf{x})$$

How?

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How?

Standard deep learning:

- | need labeled data, i.e. inputs for which we know the true output:  $(\mathbf{x}_i; f(\mathbf{x}_i))$
- | train neural network parameters to minimize the **loss function**

$$L := \frac{1}{N_{\text{labeled data}}} \sum_{\mathbf{x}_i} (f(\mathbf{x}_i) - N(\mathbf{x}_i))^2$$

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Deep equilibrium nets:

- | use equilibrium conditions directly as **loss function**

$$L := \frac{1}{N_{\text{path length}}} \sum_{\mathbf{x}_i \text{ on sim. path}} (\mathbf{G}(\mathbf{x}_i; N))^2$$

- | no need for labeled data!



# Training DEQNs

1. Simulate a sequence of states  $D_{\text{train}}^i = \{ \mathbf{x}_1^i, \mathbf{x}_2^i, \dots, \mathbf{x}_T^i \}$  from the policy encoded by the network parameters  $\rho^i$ .
2. Evaluate the errors of the equilibrium conditions on the newly generated set  $D_{\text{train}}^i$ .
3. If the error statistics are not low enough:
  - 3.1 update the parameters of the neural network with a gradient descent step (or a variant):

$$\rho_k^{i+1} = \rho_k^i - \alpha_{\text{learn}} \frac{\partial \ell_{D_{\text{train}}^i}(\rho^i)}{\partial \rho_k^i}.$$

- 3.2 set new starting states for simulation:  $\mathbf{x}_0^{i+1} = \mathbf{x}_T^i$ .
  - 3.3 increase  $i$  by one and go back to step 1.

# Illustrative Model

# Illustrative OLG model with capital and bond

| Representative firm produces with

$$F(z_t; K_t; L) = z_t K_t^\alpha L^{1-\alpha}$$

$$w_t = z_t K_t^{\alpha-1} L^{1-\alpha}$$

$$r_t = z_t (1-\alpha) K_t^{\alpha} L^{-\alpha}$$

| Uncertainty in TFP  $z_t$ , and depreciation of capital  $\delta$

$$\log(z_{t+1}) = \delta \log(z_t) + \epsilon_t$$

$$\epsilon_t \sim N(0, 1)$$

$$\delta = \frac{2}{1+\alpha}$$

| Assets

- | one period bond with price  $p_t$  in aggregate supply  $B$
- | risky capital  $K_t$
- | borrowing constraints on both assets

$$b_t^h \leq 0$$

$$k_t^h \leq 0$$

| Households

- |  $H = 32$  age-groups, indexed with  $h \in H := \{1, \dots, 32\}$
- | supply labor units  $l_t^h$  inelastically
- | adjustment costs on capital

$$\Delta_{k,t}^h := k_{t+1}^h - k_t^h$$

$$\text{adj. costs} = \frac{\gamma}{2} (\Delta_{k,t}^h)^2$$

| budget constraint

$$c_t^h = l_t^h w_t + b_t^h \frac{1}{p_t} + k_t^h \frac{1}{p_t} (1 - \delta + r_t)$$

$$p_t^b b_t^h - k_t^h - \frac{\gamma}{2} (\Delta_{k,t}^h)^2$$

| maximize

$$E \left[ \sum_{i=h}^H \beta^i u(c_{t+i}^h) \right]$$

$$u(c) := \frac{c^{1-\gamma}}{1-\gamma}$$

# Equilibrium conditions

| Market clearing:

$$K_t := \sum_{h \in H} k_t^h$$

$$B = \sum_{h \in H} b_t^h, \quad \epsilon_t^B := B - \sum_{h \in H} b_t^h = 0$$

| Firms optimize:

$$w_t := \alpha z_t K_t^{\alpha-1} L_t^{1-\alpha}$$

$$r_t := z_t (1 - \alpha) K_t^{\alpha} L_t^{-\alpha}$$

| Households optimize:

- |  $H$  sets of Karush Kuhn Tucker conditions for bond
  - ) single equation using the Fisher-Burmeister equation
  - )  $H$  errors  $\epsilon_t^{k,i}$
- |  $H$  sets of Karush Kuhn Tucker conditions for capital
  - ) single equation using the Fisher-Burmeister equation
  - )  $H$  errors  $\epsilon_t^{h,i}$

# Approximation with standard DEQN

- | State of the economy

$$\mathbf{x}_t = [ \underbrace{z_t}_{\text{ex. shock}}, \underbrace{k_t^1, \dots, k_t^{32}}_{\text{dist. of cap.}}, \underbrace{b_t^1, \dots, b_t^{32}}_{\text{dist. of bonds}} ]$$

- | Equilibrium policies

$$\mathbf{f}(\mathbf{x}_t) = [ \underbrace{k_{t+1}^1, \dots, k_{t+1}^{32}}_{\text{capital policy}}, \underbrace{b_{t+1}^1, \dots, b_{t+1}^{32}}_{\text{bond policy}}, \underbrace{\rho_t^b}_{\text{bond price}} ]$$

- | Neural network approximates

$$\mathcal{N}(\mathbf{x}_t) = [ \underbrace{\hat{k}_{t+1}^1, \dots, \hat{k}_{t+1}^{32}}_{\text{capital policy}}, \underbrace{\hat{b}_{t+1}^1, \dots, \hat{b}_{t+1}^{32}}_{\text{bond policy}}, \underbrace{\hat{\rho}_t^b}_{\text{bond price}} ] \mathbf{f}(\mathbf{x}_t)$$

- | Loss function

$$\ell(\mathbf{x}_t) := \underbrace{w_{hh;k}}_{\text{weight}} \underbrace{\left( \sum_{h=1}^H \left( \epsilon_t^{k,h} \right)^2 \right)}_{\text{opt. cond. cap.}} + \underbrace{w_{hh;b}}_{\text{weight}} \underbrace{\left( \sum_{h=1}^H \left( \epsilon_t^{b,h} \right)^2 \right)}_{\text{opt. cond. bond}} + \underbrace{w_{mc;B}}_{\text{weight}} \underbrace{\left( \epsilon_t^B \right)^2}_{\text{market clearing}}$$

# Innovation 1: Market clearing layers

- Neural network first predicts

$$N^{\text{pre}}(\mathbf{x}_t) = [\hat{k}_{t+1}^1; \dots; \hat{k}_{t+1}^{32}; \hat{b}_{t+1}^1; \dots; \hat{b}_{t+1}^{32}; \hat{\rho}_t^b]$$

- Apply transformation  $m(\dots; )$

$$[\hat{b}_{t+1}^1; \dots; \hat{b}_{t+1}^{32}] = m(N^{\text{pre}}(\mathbf{x}_t); B)$$

- Such that

$$B = \sum_{h=1}^{32} \hat{b}_{t+1}^h$$

- Put together

$$N(\mathbf{x}_t) := [\hat{k}_{t+1}^1; \dots; \hat{k}_{t+1}^{32}; \hat{b}_{t+1}^1; \dots; \hat{b}_{t+1}^{32}; \hat{\rho}_t^b]$$

- Loss function now

$$\mathcal{L}(\mathbf{x}_t) := \underbrace{W_{hh,k}}_{\text{weight}} \underbrace{\left( \sum_{h=1}^H \left( \binom{k}{t}^{k,h} \right)^2 \right)}_{\text{opt. cond. cap.}} + \underbrace{W_{hh,b}}_{\text{weight}} \underbrace{\left( \sum_{h=1}^H \left( \binom{b}{t}^{b,h} \right)^2 \right)}_{\text{opt. cond. bond}} + \underbrace{W_{mc,B}}_{\text{weight}} \underbrace{\left( \frac{B}{t} \right)^2}_{\text{market clearing}}^* = 0$$

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- no need to learn economics we already know ex-ante
- remaining loss easier to interpret
- states simulated from the policy are always consistent with market clearing

► details

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- | **Why?**
  - | portfolio choice only pinned down at low errors in equilibrium conditions
  - | but how do we get there?

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  1.  $N - 1$  asset models are nested in  $N$  asset models

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  2. start with single asset model

$$N^1(\mathbf{x}_t) = [\hat{k}_{t+1}^1, \dots, \hat{k}_{t+1}^{32}, \mathbf{0}, \hat{b}_{t+1}^1, \dots, \mathbf{0}, \hat{b}_{t+1}^{32}, \hat{\rho}_t^b], B^1 = \mathbf{0}$$

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3. solve the model

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4. train the neural network to predict the bond price (**supervised, from zero liquidity limit**)

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3. solve the model
4. train the neural network to predict the bond price (**supervised, from zero liquidity limit**)
5. slowly introduce the second asset (**such that the error remains low**)

$$N^2(\mathbf{x}_t) = [\hat{k}_{t+1}^1, \dots, \hat{k}_{t+1}^{32}, 1 \quad \hat{b}_{t+1}^1, \dots, 1 \quad \hat{b}_{t+1}^{32}, \rho_t^b], B^2 = 0.1$$

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$$N^4(\mathbf{x}_t) = [\hat{k}_{t+1}^1, \dots, \hat{k}_{t+1}^{32}, 1 \quad \hat{b}_{t+1}^1, \dots, 1 \quad \hat{b}_{t+1}^{32}, \rho_t^b], B^4 = 0.3$$

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$$N^5(\mathbf{x}_t) = [\hat{k}_{t+1}^1, \dots, \hat{k}_{t+1}^{32}, 1 \quad \hat{b}_{t+1}^1, \dots, 1 \quad \hat{b}_{t+1}^{32}, \rho_t^b], B^5 = 0.4$$

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$$N^{\dots}(\mathbf{x}_t) = [\hat{k}_{t+1}^1, \dots, \hat{k}_{t+1}^{32}, \mathbf{1} \quad \hat{b}_{t+1}^1, \dots, \mathbf{1} \quad \hat{b}_{t+1}^{32}, \rho_t^b], B^{\dots} = \dots$$

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$$N^{100}(\mathbf{x}_t) = [\hat{k}_{t+1}^1, \dots, \hat{k}_{t+1}^{32}, 1, \hat{b}_{t+1}^1, \dots, 1, \hat{b}_{t+1}^{32}, \rho_t^b], B^{100} = 10$$

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6. equilibrium errors **always remain low**

# Application

# Step 1: Solve single asset model

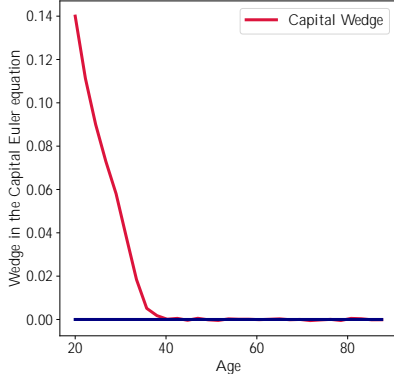
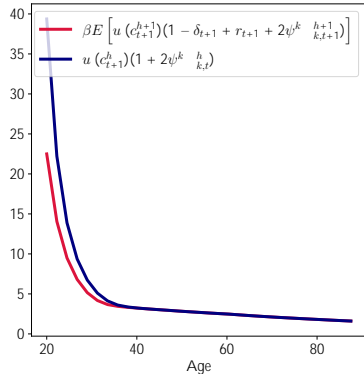
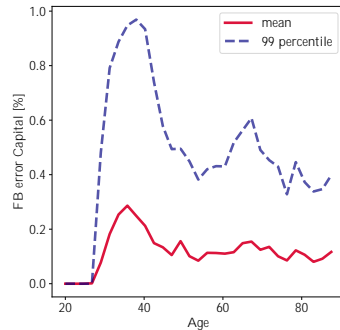
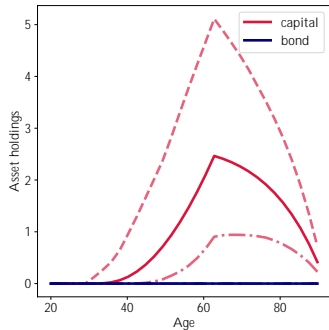
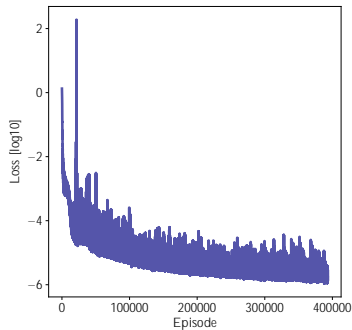
- | Borrowing constraint  $\underline{b} = 0$ , net-supply  $B = 0$
- | Neural network predicts

$$N^{\text{pre}}(\mathbf{x}_t) = [\hat{k}_{t+1}^1, \dots, \hat{k}_{t+1}^{32}, 0, \tilde{b}_{t+1}^1, \dots, 0, \tilde{b}_{t+1}^{32}, \rho_t^b]$$

$$) N(\mathbf{x}_t) = [\hat{k}_{t+1}^1, \dots, \hat{k}_{t+1}^{32}, 0, \dots, 0, \rho_t^b]$$

- | Loss function

$$\ell(\mathbf{x}_t) := \underbrace{1 \left( \sum_{h=1}^{H-1} (\epsilon_t^{k;h})^2 \right)}_{\text{opt. cond. cap.}} + \underbrace{0 \left( \sum_{h=1}^{H-1} (\epsilon_t^{b;h})^2 \right)}_{\substack{\text{opt. cond. bond} \\ =0}}$$





# Step 2: Pre-train bond price in the capital only model

- Keep borrowing constraint  $\underline{b} = 0$ , net-supply  $B = 0$ , and neural network masks

$$N(\mathbf{x}_t) = [\hat{k}_{t+1}^1; \dots; \hat{k}_{t+1}^{32}; 0; \dots; 0; \hat{p}_t^b]$$

- In equilibrium we know that

$$p_t^b = \frac{E[u^0(c_{t+1}^{h+1})]}{u^0(c_t^h)}$$

with equality for unconstrained agents.

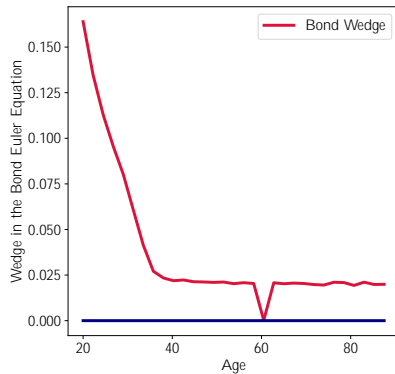
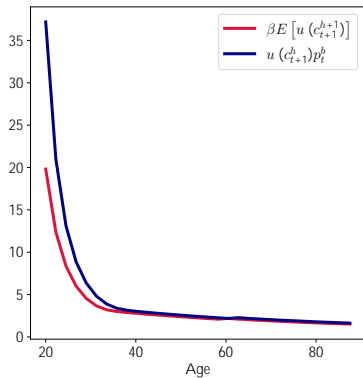
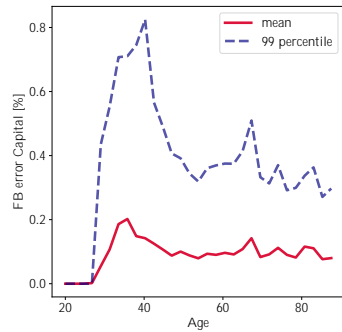
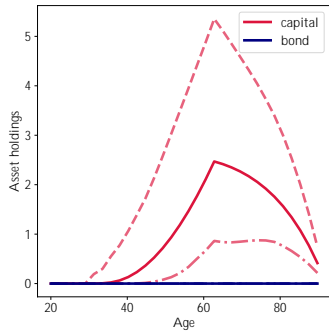
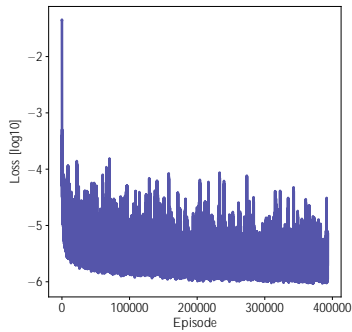
- With **market clearing policies**, we have a **closed form expression for the bond price** and can define pre-train price and error

$$p_t^{b, \text{pre-train}} := \max_{h \geq H} \left\{ \frac{E[u^0(c_{t+1}^{h+1})]}{u^0(c_t^h)} \right\}$$

$$p_t^{\text{pre-train}} := p_t^{b, \text{pre-train}} \hat{p}_t^b$$

- Loss function

$$L(\mathbf{x}_t) := \underbrace{1 \left( \sum_{h=1}^{H-1} \left( \hat{k}_t^{k,h} \right)^2 \right)}_{\text{opt. cond. cap.}} + \underbrace{0 \left( \sum_{h=1}^{H-1} \left( \hat{b}_t^{b,h} \right)^2 \right)}_{\substack{\text{opt. cond. bond} \\ =0}} + \underbrace{1 \left( \hat{p}_t^{\text{pre-train}} \right)^2}_{\substack{\text{price pre-train error} \\ \text{train supervised}}}$$



# Step 3: Slowly increase bond supply

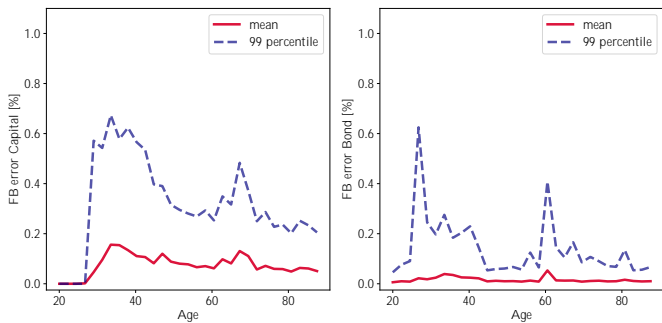
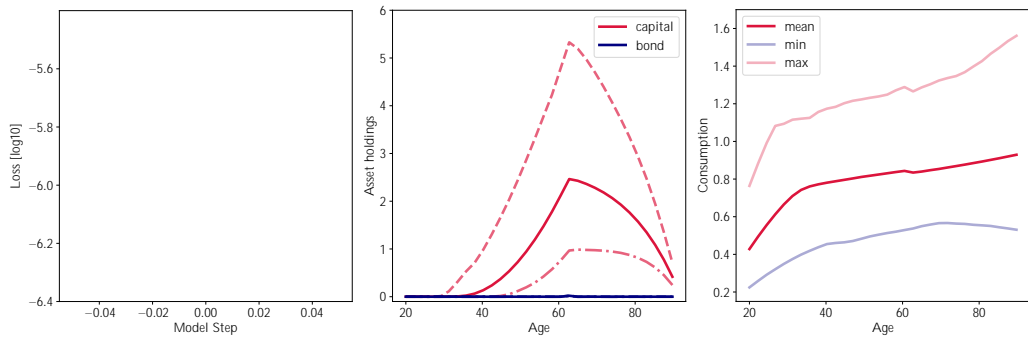
- | Borrowing constraint  $\underline{b} = 0$ , increase net-supply from  $B = 0.1$  to  $B = 10$
- | Neural network predicts

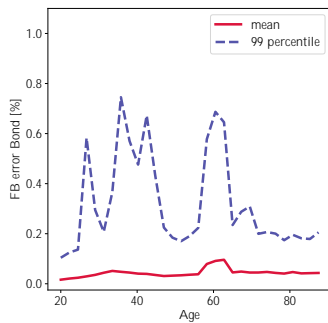
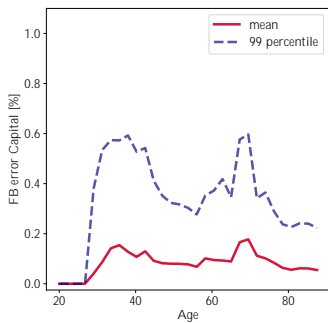
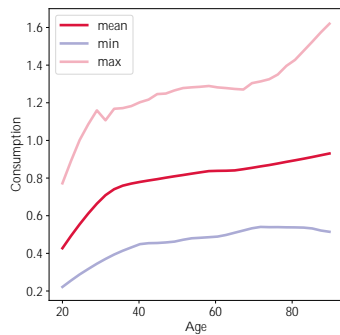
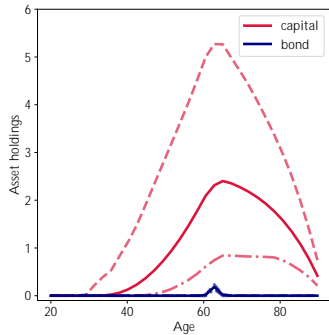
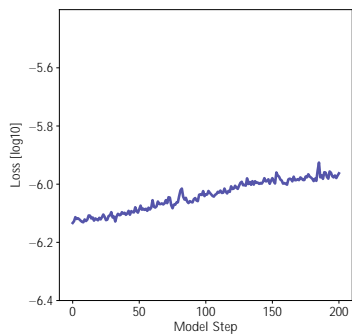
$$N^{\text{pre}}(\mathbf{x}_t) = [\hat{k}_{t+1}^1, \dots, \hat{k}_{t+1}^{32}, \underbrace{0.01 \tilde{b}_{t+1}^1, \dots, 0.01 \tilde{b}_{t+1}^{32}}_{\text{bond policies active}}, \rho_t^b]$$

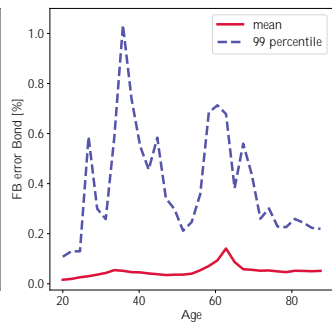
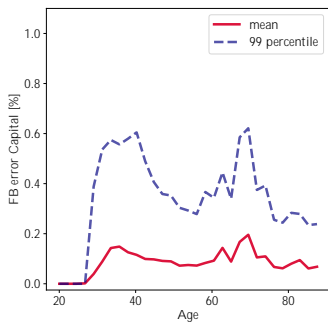
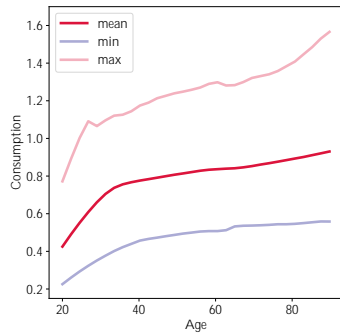
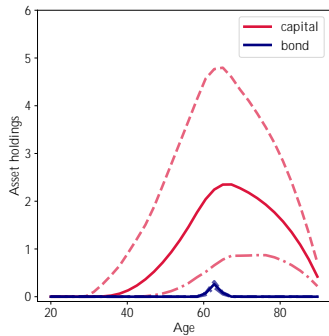
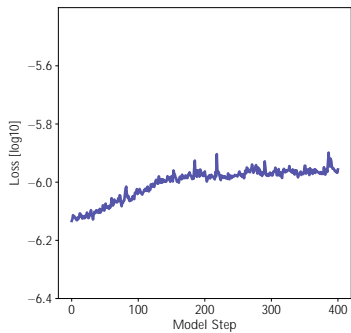
$$) \quad N(\mathbf{x}_t) = [\hat{k}_{t+1}^1, \dots, \hat{k}_{t+1}^{32}, \underbrace{\hat{b}_{t+1}^1, \dots, \hat{b}_{t+1}^{32}}_{\text{always add up the B}}, \rho_t^b]$$

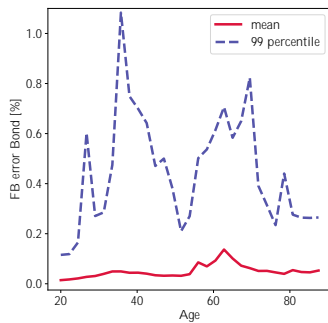
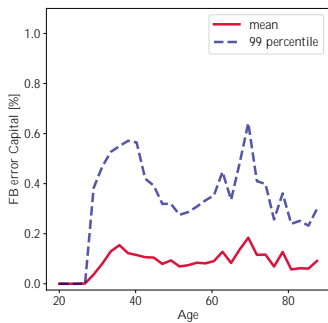
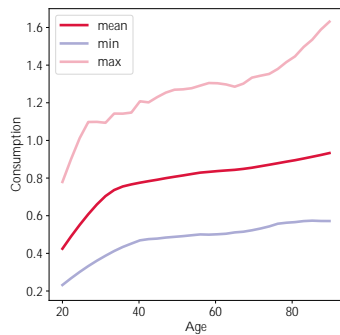
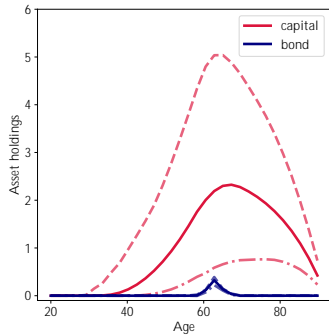
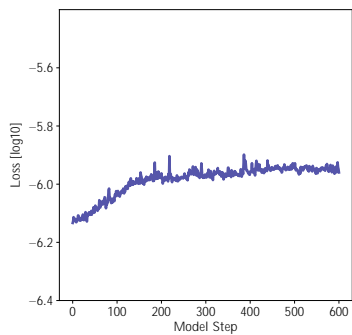
- | Loss function

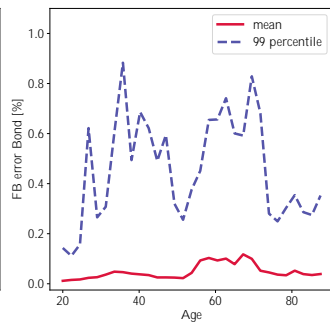
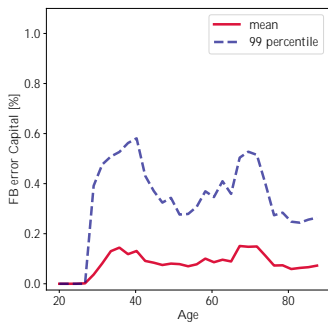
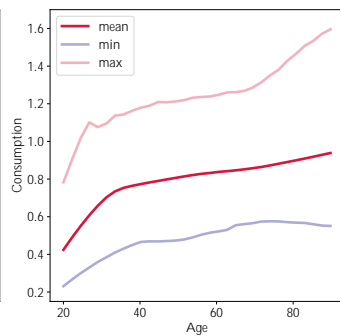
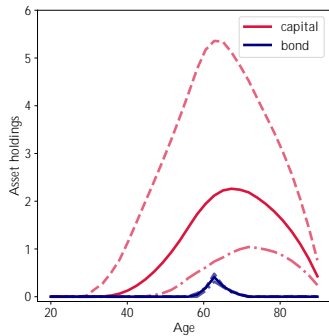
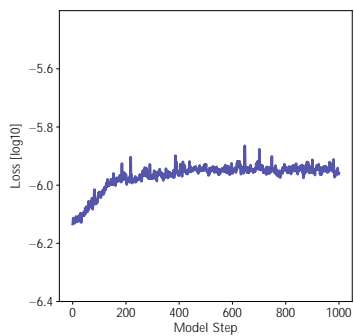
$$\ell(\mathbf{x}_t) := \underbrace{1 \left( \sum_{h=1}^H \left( \epsilon_t^{k;h} \right)^2 \right)}_{\text{opt. cond. cap.}} + \underbrace{1}_{\text{bond equ. cond. active}} \underbrace{\left( \sum_{h=1}^H \left( \epsilon_t^{b;h} \right)^2 \right)}_{\text{opt. cond. bond}}$$



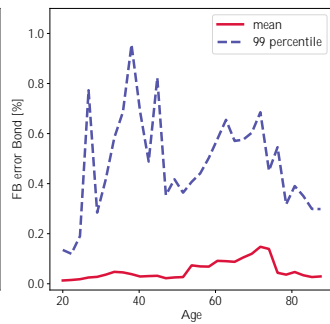
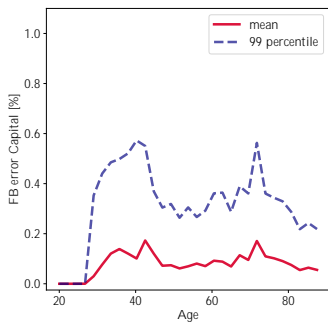
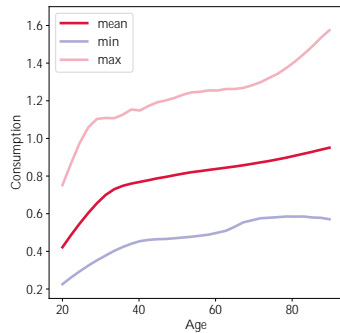
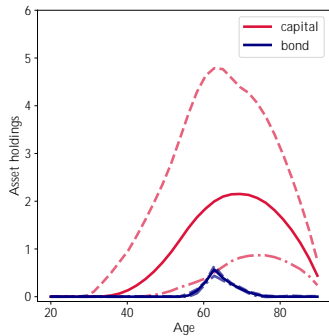
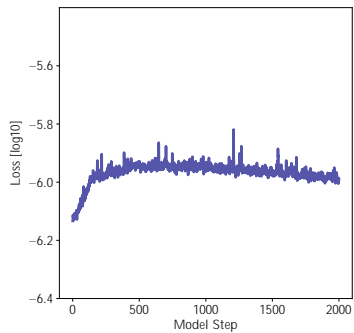


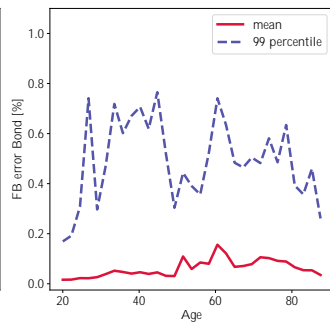
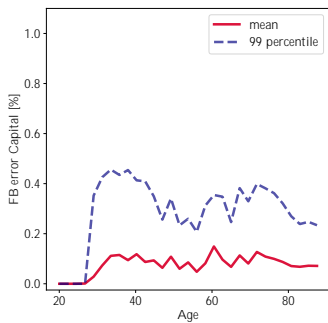
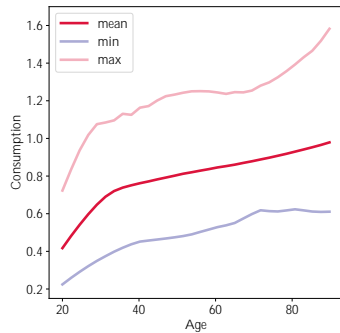
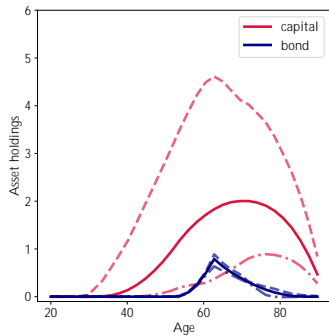
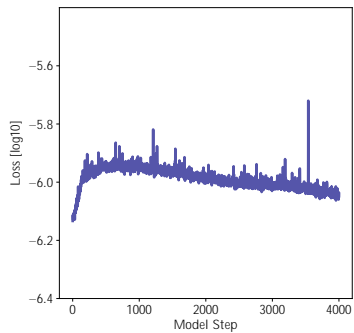


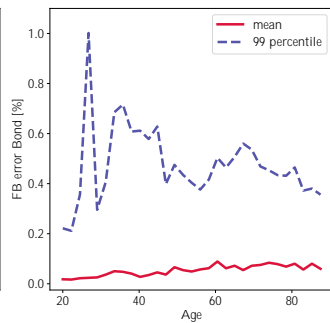
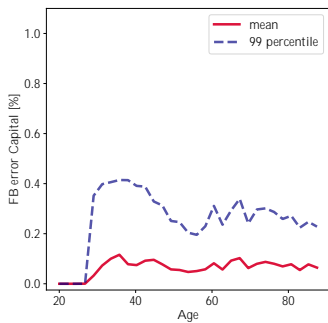
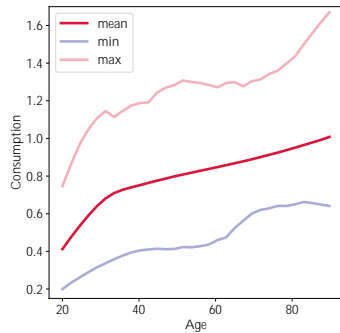
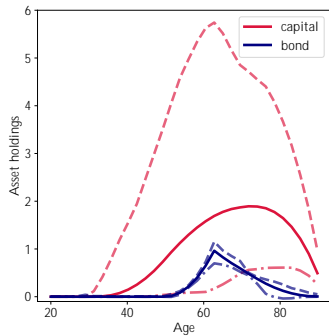
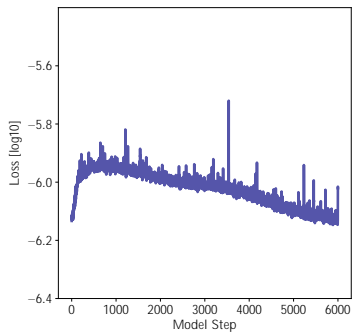


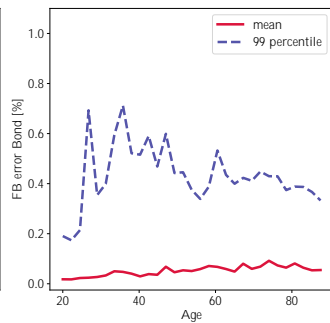
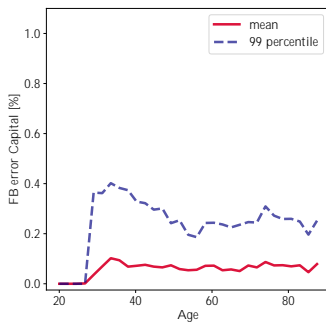
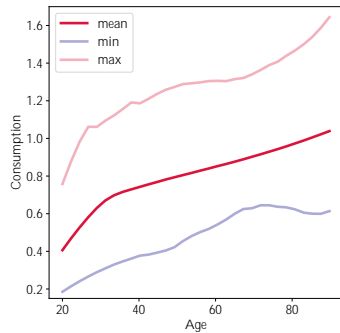
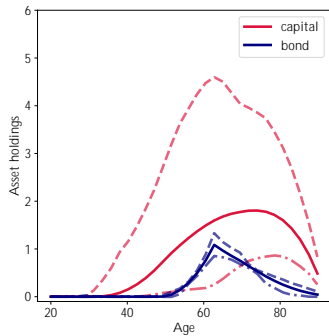
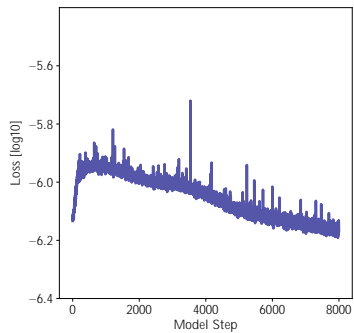


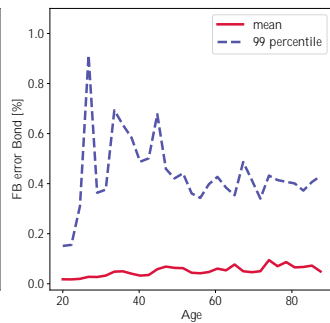
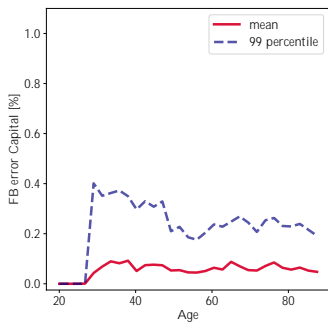
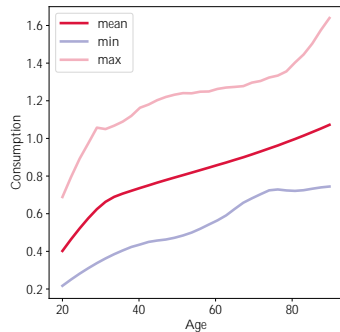
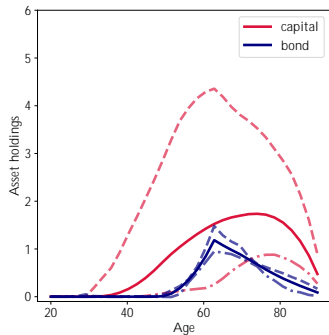
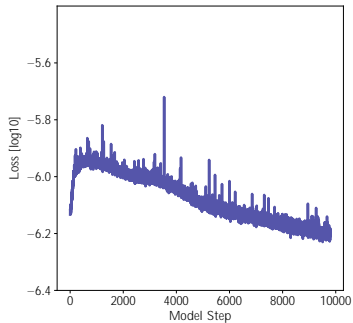












## Step 4: Training with the final supply

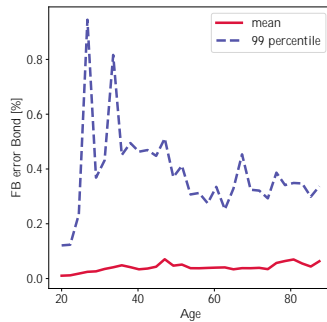
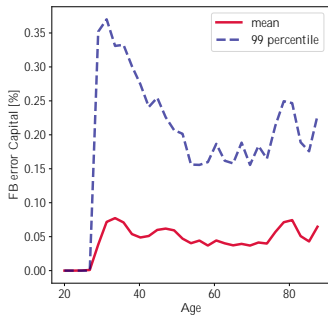
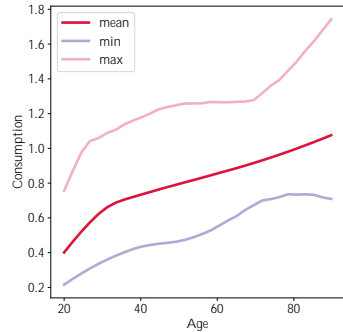
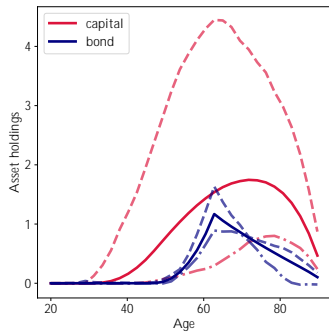
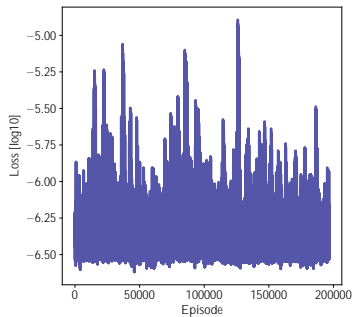
- | Borrowing constraint  $\underline{b} = 0$ , bond at full net-supply from  $B = 10$
- | Neural network predicts

$$N^{\text{pre}}(\mathbf{x}_t) = [\hat{k}_{t+1}^1, \dots, \hat{k}_{t+1}^{32}, \underbrace{0.01 \tilde{b}_{t+1}^1, \dots, 0.01 \tilde{b}_{t+1}^{32}}_{\text{bond policies active}}, \rho_t^b]$$

$$) \quad N(\mathbf{x}_t) = [\hat{k}_{t+1}^1, \dots, \hat{k}_{t+1}^{32}, \underbrace{\hat{b}_{t+1}^1, \dots, \hat{b}_{t+1}^{32}}_{\text{always add up the B}}, \rho_t^b]$$

- | Loss function contains all remaining equilibrium conditions

$$\ell(\mathbf{x}_t) := \mathbf{1} \underbrace{\left( \sum_{h=1}^{H-1} (\epsilon_t^{k;h})^2 \right)}_{\text{opt. cond. cap.}} + \mathbf{1} \underbrace{\left( \sum_{h=1}^{H-1} (\epsilon_t^{b;h})^2 \right)}_{\text{opt. cond. bond}}$$



# Conclusion



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- | Deep neural networks are promising to approximate nonlinear functions on high-dimensional domains
- | Key ideas in Azinovic et al. (2022):
  - | **minimizing the error in the equilibrium conditions** allows training the neural network without labeled data ) neural network can be trained on billions of states
  - | training on the **simulated path** ) focus training on where it matters
- | Models with many assets remain challenging. To address this issue Azinovic and Žemlička (2023) introduce key innovations
  - | **market clearing layers**, an economics-inspired neural network architecture
  - | **step-wise model transformation** procedure to guide network training with many assets

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- | Also in the paper: quantitative life-cycle model with disaster risk, housing, equity and bonds in general equilibrium to study the intergenerational consequences of rare disasters (updated version coming soon)
- | Other cool papers on deep learning based solution methods: Maliar et al. (2021); Kase et al. (2023); Gu et al. (2023); Kahou et al. (2021); Han et al. (2022); Valaitis and Villa (2024); Kahou et al. (2022); Fernández-Villaverde et al. (2023); Barnett et al. (2023); Jungerman (2023); Kahou et al. (2024)

Thank you!

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# Deep Neural Networks

# What is a deep neural net?

Consider:

$$\text{input} := \mathbf{x} \quad / \quad W^1 \mathbf{x} + \mathbf{b}^1 =: \text{hidden 1}$$



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$$\begin{aligned} \text{input} &:= \mathbf{x} \quad / \quad W^1 \mathbf{x} + \mathbf{b}^1 =: \text{hidden 1} \\ / \quad \text{hidden 1} & \quad / \quad W^2(\text{hidden 1}) + \mathbf{b}^2 =: \text{hidden 2} \end{aligned}$$

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$$\begin{aligned} \text{input} &:= \mathbf{x} \quad / \quad W^1 \mathbf{x} + \mathbf{b}^1 =: \text{hidden 1} \\ / \quad \text{hidden 1} & \quad / \quad W^2(\text{hidden 1}) + \mathbf{b}^2 =: \text{hidden 2} \\ / \quad \text{hidden 2} & \quad / \quad W^3(\text{hidden 2}) + \mathbf{b}^3 =: \text{output} \end{aligned}$$

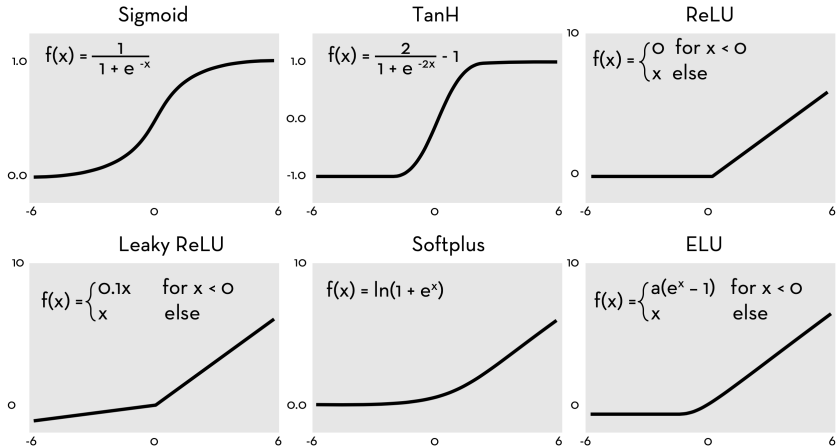
The parameters of this procedure are the entries of the matrices ( $W^1$ ,  $W^2$ ,  $W^3$ ) and vectors ( $\mathbf{b}^1$ ,  $\mathbf{b}^2$ ,  $\mathbf{b}^3$ ).

# What is a deep neural net? (cont.)

So far we have a concatenation of affine maps and therefore an affine map.

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So far we have a concatenation of affine maps and therefore an affine map.  
Next ingredient: activation functions  $\phi^1, \phi^2, \phi^3$ . Activation functions could be any function, but popular are:



# What is a deep neural net? (cont.)

Now we get:

$$\begin{aligned} \text{input} &:= \mathbf{x} / \phi^1(W^1\mathbf{x} + \mathbf{b}^1) =: \text{hidden 1} \\ / \text{ hidden 1} &/ \phi^2(W^2(\text{hidden 1}) + \mathbf{b}^2) =: \text{hidden 2} \\ / \text{ hidden 2} &/ \phi^3(W^3(\text{hidden 2}) + \mathbf{b}^3) =: \text{output} \end{aligned}$$

The neural net is then given by the choice of activation functions and the parameters .

▶ back

# Why neural networks?

Approximation method	High-dimensional input	Can resolve local features accurately	Irregularly shaped domain	Large amount of data
Polynomials	✓	✗	✓	✓
Splines	✗	✓	✗	✓
Adaptive (sparse) grids	✓	✓	✗	✓
Gaussian processes	✓	✓	✓	✗
Deep neural networks	✓	✓	✓	✓

**Table:** Taken from Azinovic et al. (2022).

# Innovation 1: Details on the market clearing transformation function

- | Simple market clearing layer: subtract excess demand  $ED_t$  from initial predictions

$$ED_t := \sum_{h \in H} b_{t+1}^h - B$$

$$\hat{b}_{t+1}^h := b_{t+1}^h - \frac{1}{H} ED_t$$

- | Why this adjustment?
- ! we try to minimize the modification to the initial predictions  $f b_{t+1}^h g_{h \in H}$ .
- | Final predictions  $f \hat{b}_{t+1}^h g_{h \in H}$  solve

$$\arg \min_{f x_{t+1}^h g_{h \in H}} \sum_{h \in H} \left( x_{t+1}^h - b_{t+1}^h \right)^2$$

subject to

$$\sum_{h \in H} x_{t+1}^h = B$$



# Innovation 1: Details on the market clearing transformation function

- | Simple market clearing layer: subtract excess demand  $ED_t$  from initial predictions

$$ED_t := \sum_{h \in H} b_{t+1}^h - B$$

$$\hat{b}_{t+1}^h := b_{t+1}^h - \frac{1}{H} ED_t$$

- | Why this adjustment?
- ! we try to minimize the modification to the initial predictions  $f b_{t+1}^h g_{h \in H}$ .
- | Final predictions  $f \hat{b}_{t+1}^h g_{h \in H}$  solve

$$\arg \min_{f x_{t+1}^h g_{h \in H}} \sum_{h \in H} \left( x_{t+1}^h - b_{t+1}^h \right)^2$$

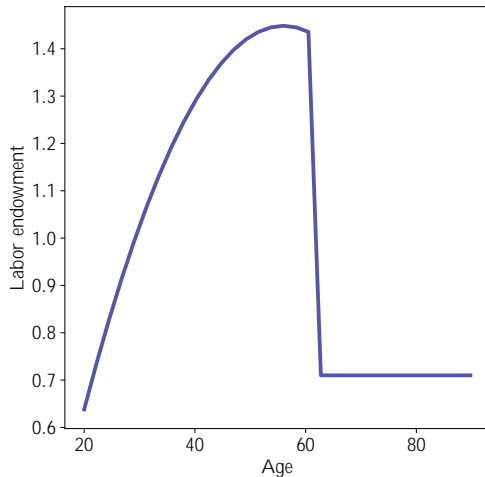
subject to

$$\sum_{h \in H} x_{t+1}^h = B$$

- | In the paper: enforcing market clearing & borrowing constraints using **implicit layer**

# Parameters

Parameters	$H$						
Values	32	0.912	4	0.1	0.693	0.052	0.333
Meaning	num. age groups	patience	RRA	adj. costs	pers. tfp	std. innov. tfp	cap. share



# Households' optimality conditions

$$\left. \begin{array}{l} 1 \\ k_t^h \\ k_t^h \\ k_t^h \\ = 0 \end{array} \right\} = \frac{\beta E \left[ u^0(c_{t+1}^{h+1}) (1 - \delta_{t+1} + r_{t+1} + 2\psi^k \Delta_{k,t}^{h+1}) + \mu_t^h \right]}{(1 + 2\psi^k \Delta_{k,t}^h) u^0(c_t^h)} \quad , \quad k_t^{,h} := FB \left( \frac{u^0 \cdot 1 \left( E \left[ u^0(c_{t+1}^{h+1}) \frac{(1 - \delta_{t+1} + r_{t+1} + 2\psi^k \Delta_{k,t}^{h+1})}{(1 + 2\psi^k \Delta_{k,t}^h)} \right] \right)}{c_t^h} \quad ; \quad \frac{k_t^h}{c_t^h} \right)$$

$$\left. \begin{array}{l} 1 \\ b_t^h \\ (b_t^h \quad \underline{b}^h) \\ \underline{b}^h \\ = 0 \end{array} \right\} = \frac{\beta E \left[ u^0(c_{t+1}^{h+1}) \right] + \lambda_t^h}{p_t^h u^0(c_t^h)} \quad , \quad b_t^{,h} := FB \left( \frac{u^0 \cdot 1 \left( E \left[ \frac{1}{p_t^h} u^0(c_{t+1}^{h+1}) \right] \right)}{c_t^h} \quad ; \quad \frac{b_t^h}{c_t^h} \quad \underline{b} \right)$$

where

$$FB(a; b) := a + b \sqrt{a^2 + b^2}$$

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